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Monterey, California



DESIGN MANUAL FOR THE
VECTOR GENERAL GRAPHICS DISPLAY UNIT

by

L. A. Thorpe

G. M. Raetz

March 1976

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Monterey, California

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ABSTRACT

This report describes the program description of an interactive graphics package interfacing the Vector General Graphics Display Unit and a Digital Equipment Corporation PDP-11/50 computer. The program was written in the C-programming language and designed to be used in the multiprogramming environment of the UNIX Timesharing operating system. Included is a description of the Vector General, operating system modifications, device driver, and interface routines.

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I. INTRODUCTION

This manual is the program description for an interactive graphics package interfacing a Vector General Graphics Display System and a PDP-11/50 user. The Vector General Graphics Display System (vector general) is an interactive graphics cathode ray tube (CRT) display that is connected to the PDP-11/50 computer via a modified DR11-B interface. The display interacts with an on-line user by displaying pictorial information on the surface of the cathode ray tube and by accepting inputs from external control devices. The inputs are requested and processed by computer programs that alter and maintain the output picture being presented to the user.

This manual assumes that the reader is familiar with the C-programming language and the UNIX operating system. The terminology used herein without explanation refers to the features and registers in the display unit. A more detailed description can be found in the Vector General Graphics Display Unit Reference Manual (VG 101056). A user's manual is published separately.

The software design can be divided into five major categories:

1. Modifications to UNIX
2. System Routines

3. Memory Allocation
4. User Interrupt Routines
5. User Interface Routines

The remaining sections of this manual describe these divisions. References are repeatedly made to object lists, object buffer lists, and element lists. These formats can be found in Appendix A. Many external global variables are used by the various display routines. These variables are described in Appendix B. The many "defines" are detailed in Appendix C.

The general design for the display software is such that all routines, defines, and external names (UNIX modifications and system routines excluded) are archived in a system library, /lib/libv.a. The user can then include this file at compile time and have access to the entire display software for his use. As a result, the convention has been adopted that all routines and global variables begin with "vg". This avoids collision of name definition if the user avoids names starting with "vg".

II. MODIFICATIONS TO UNIX

The memory allocation scheme of UNIX had to be modified to permit the Vector General Graphics Display System to access the display list. A real-time system call,

rttime(), has been added to make the calling process real-time by relocating the process continuously within a thirty-two thousand three hundred sixty-eight byte memory block. The memory allocation of the process is not allowed to cross a memory address that is a multiple of thirty-two thousand three hundred sixty-eight. This allows the vector general display to programmatically address any of the thirty-two thousand three hundred sixty-eight memory addresses without resetting the extended memory bits. The rttime() call also sets the process priority so that the operating system will not swap the process onto the disk. This locks the process into a fixed memory area. The real-time process can then dynamically modify the display list while the vector general is continuously accessing the same display list via its direct memory access channel.

Because of the requirement to lock a real-time process into a fixed memory area, the operating system permits only a limited number of simultaneous real-time processes. If the required memory area is allocated to another non-swappable process or the maximum number of real-time processes has been previously allocated, the requested process is not made real-time and an error is returned to the caller.

III. SYSTEM ROUTINES

The vector general has been divided into six minor devices. This simplifies the communication between the user and the device driver. Each minor device has associated with it a flag that is set in response to the user's `open()` command. Since the vector general is a dedicated device, any attempt to share the vector general between users or use the vector general without opening all minor devices will result in an error to the caller. After all six minor devices have been opened, a single vector general system flag, `valock`, is set. This system lock is checked prior to any read or write operation. In addition the process is made real-time, the user process number is retained in `vgproc`, and the display is flagged as idle. The user process number is used to pass the vector general interrupts to the user via `psignal()`. The display idle flag allows the initial display list to start the vector general but prevents subsequent display lists from abnormally terminating a previous display list.

Initialization of user controlled parameters is usually the next requirement. When the user issues a `write()` command via minor device two, `VGCNTRL`, the contents of the user's buffer is interpreted as the refresh reference count. This determines the number of vector general frame clock interrupts permitted before reinitialization of the

display list.

The vector general subroutine stack option permits accessing non-contiguous display lists. However, the vector general must have the memory address of any non-contiguous display lists encoded within a contiguous display list. This requires the user to have access to the real PDP-11 memory addresses of his display lists. The mapping of user space to real memory addresses is accomplished by the user's issuance of a write() command followed by a read() command via minor device zero, VG. The write command stores the real PDP-11 memory address of the user buffer in the variable vgaddr. The user's read command passes the value of the real PDP-11 memory address to the user via the passc() routine.

When dynamically modifying display lists, the memory address encoded in a display must often be converted to a user space address for referencing a user's display list. This capability is provided by a read() command using minor device five, VGCVI. The base block number of the user's process obtained by the vstrategy() routine is passed to the user via passc().

When the user has created the display, he must pass the address of the display list to the vector general. The user's write() command using minor device one, VGDISP, accomplishes this task. The lower sixteen bits of the address are stored in baddr1. The upper two bits are encoded in baddrx. If the display has not been

initialized, the routine `vastart()` sends the address to the vector general and starts the vector general's operation. If the display has been initialized, the new address in `baddr1` represents a new display list to be used after completing the active display list.

The vector general operates independent of the user process after being given a display list. However, communication with the system routines is maintained via interrupts. A frame clock interrupt signal is generated every 8.33 milliseconds and a device interrupt is generated whenever the user operates one of the enabled peripheral devices. The frame clock interrupt increments a counter until the counter equals the refresh reference count. At that time the display is reinitiated by a call to `vastart()`.

The device interrupt handler passes the interrupt to the user via signal number two or fifteen. All device interrupts except the ASCII `CTRL I` character are passed to the user via signal fifteen. The ASCII `CTRL I` character input via the vector general keyboard is interpreted as a control key terminating the process, causing the display to be cleared, and notifying the user via signal two. Occasionally, the user may desire the `CTRL I` character as data. This is provided by input of the `ESC` character from the vector general keyboard. This results in the next interrupt being sent to the user regardless of the type or content. Each device interrupt also causes

the values of various vector general registers to be extracted and stored in `vdbuf[]` for transfer to the user.

The transfer of the vector general register values to the user can be accomplished in several different ways. The most common is in response to a device interrupt. The user can acquire the interrupt state of the vector general (except the dial positions) by issuing a `read()` command using minor device one, `VGDISP`. The contents of `vdbuf[]` are passed to the user via the `passc()` routine. The user's `read()` command with minor device two, `VGDTRL`, will force an update of the `vdbuf[]` before passing the values to the user. When minor device three, `VGFNSW`, is used in a read operation, the values of the function switches are updated prior to sending `vdbuf[]` to the user. `VGDIAL`, minor device four, extracts the values of the ten dial positions before transmission of `vdbuf[]`. The vector general dial positions are acquired via a separate `read()` command because sixteen microseconds are required to read each dial position to the full twelve bit precision.

The vector general's P-bit interrupt is not utilized in this software interface. Therefore, the P-bit interrupt handler is an empty routine.

The source code for the system routines is maintained in `/usr/sys/dmr/vgdrv.c`. A copy of `vgdrv.c` is included as Appendix D.

IV. MEMORY ALLOCATION

A. FIXED MEMORY ALLOCATION

The user space memory allocation for the vector general registers and the picture display list use an unorthodox technique to obtain sequential memory locations. All the integer variables defined in the file `vqreg.h` correspond to the named vector general registers. The order of the variables is the order in which the values are read from the vector general. Because the loader assigns variables sequentially, this technique allows the variables to be referenced by incrementing an address pointer without requiring a structure definition.

The file `vqsys.h` contains a similar sequence of integer variables used as the display list for initializing the picture parameters. Each integer variable of this file is a vector general command or a vector general data word. The order of the variables cannot be changed without affecting the operation of the vector general.

B. TUNABLE MEMORY ALLOCATION

The arrays and vectors that directly limit the size of the interface data structure are defined in the files `vqglob.h` and `vqobj.h`. When specific applications require

the interface data structure to be altered, the define statements used to determine all array and vector sizes are located in vodef.h. This permits any of the system parameters to be modified by referencing a single file.

V. USER INTERRUPT ROUTINES

A. INTERRUPT HANDLER (vdpiv)

The basic interrupt handler, vdpiv(), is called in response to signal fifteen from the system device interrupt handler. To determine which vector general device caused the interrupt, vdpiv() obtains the interrupt state of the vector general via the user interface routine vqpio(). vqpio() transfers the values of eighty-three vector general registers into eighty-three contiguous words of memory starting at the address of vqefs1. The value of the priority interrupt request register (PIR) can then be examined to determine the appropriate interrupt handler.

B. KEYBOARD CHARACTER INTERRUPT HANDLER (vgkpiv)

The keyboard character interrupt handler, `vgkpiv()`, is called when the PIK bit of the PIR register is set. The ASCII keyboard character, `vgkbr`, is placed in a circular queue, `vgkque`, and the input character flag, `vgkptr`, is incremented to the next cell in the queue. A character input flag, `vgkfla`, is incremented each time a character is input. The routine `vggetcar()` uses this flag to determine if a character has been input.

Whenever the ASCII character CTRL P is detected, `vgkque` is cleared and the flags `vgkfla` and `vgkquefl` are reset to zero. This effectively clears the input queue of all previous characters.

C. MANUAL INTERRUPT HANDLER (vgmpiv)

The manual interrupt pivot, `vgmpiv()`, handles the PIS interrupt from the vector general. The sole action of the interrupt handler is to increment a counter, `vgmanint`. This counter may be interrogated and cleared by the user.

D. LIGHT PEN INTERRUPT HANDLER (vglpiv)

The light pen interrupt handler, `vglpiv()`, is responsible for both the light pen interrupt (PIP) and the light

pen sense switch (SP1) interrupts. Each interrupt call to this routine must be processed and cleared before another light pen interrupt may be accepted. For each accepted interrupt the following vector general registers are stored in successive words of `volpbuf[]`:

Priority interrupt register (PIR)

Instruction register (IR)

Word count (WCR)

X, Y, Z coordinate registers (XR, YR, ZR respectively)

Pen resolution byte (PENR)

Whenever a light pen interrupt occurs and the light pen sense switch is processed, the counter `volpsflg` is incremented. The user is responsible for the use of this counter.

E. PROCESS TERMINATION ROUTINE (`vocrash`)

`vocrash()` is called in response to signal two. The vector general is closed via `voterm()` and the process is terminated.

VI. USER INTERFACE ROUTINES

The user interface software has been designed to make the detailed operation of the vector general transparent to the user. However, the user should be familiar with the data structure constructs used to implement the interface.

The basic concept of the user interface software is to define high level constructs which the user interface routines convert into vector general commands. There are three classes of constructs defined: objects, elements, and the picture. An object is the lowest level construct which can be displayed alone. Each object is independently rotatable, scalable, and translatable into any portion of a thirty inch by thirty inch picture space. An object can be as large as fifteen inches by fifteen inches and be rotated or positioned to the extreme limits of the picture space without distortion to any of the remaining visible portion. Each object is composed of one or more independently light pen hookable elements. An element is composed of a series of user drawn images or characters entirely relative to the untransformed image space of its object. An object can be defined unrotated in such a way as to fill the entire object space and then be scaled, rotated, and moved so that the image space is the appropriate size, is viewed from the appropriate aspect, and

is in the appropriate area of the picture. The picture defines the picture scale and screen coordinates for all objects. Figure 5-1 provides a graphic representation of the relationship between each construct.

The user is responsible for the generation and content of each element. Prior to its inclusion within the display list, the user must fill each element with the necessary draw and move commands. In addition, the user must provide three unused words succeeding the draw-move commands. These three words are used by the interface routines to ensure each element is properly terminated. This prevents the vector general from accessing memory outside the display list if the user fails to properly terminate the display list.

The generation and content of all objects and the picture is the responsibility of the interface software. A set of routines are provided to link elements to objects and objects to the picture. Dynamic modification of objects and picture parameters is also provided. However, it is the user's responsibility to dynamically modify the element content.

The following routines are normally transparent to the user and should not be accessed directly by the user.

vgctrl(addr)	vgmpiv()
vgcrash()	vgobjmod(num,fields,action)
vgconvrt(abb)	vgoinit()
vgdpiv()	vgoren()

```

vgelemod(num,fields,action)  vgnicmod(field,action)
vqkpiv()                      vgnio(hn,mode)
vgmpiv()

```

The routines that are directly accessible by the user for manipulation and modification of the display data structure are:

```

vgaddele(abb,num,size)      vginit()
vqblink(type,num,action)    vgioffset(num,val)
vgclock(rate)               vqiscal(num,val)
vgcoord(num,x,y,z)          vqlamps(abb)
vgcsr(num,val)              vqlpen(type,num,action)
vgdelele(num)               vmkobj()
vgdelobj(num)               vqpicture()
vgdial(abb)                 vqpost(px,py)
vggetcar()                  vqpscal(val)
vggetfsw(abb)               vgrotate(num,x,y,z)
vggetlph(abb)               voterm()

```

A. SUPPORTING ROUTINES

The function and operation of the routines vqcrash(), vgd piv(), vqkpiv(), vqlpiv(), and vgmpiv() have been discussed earlier. See section IV for a discussion of their function.

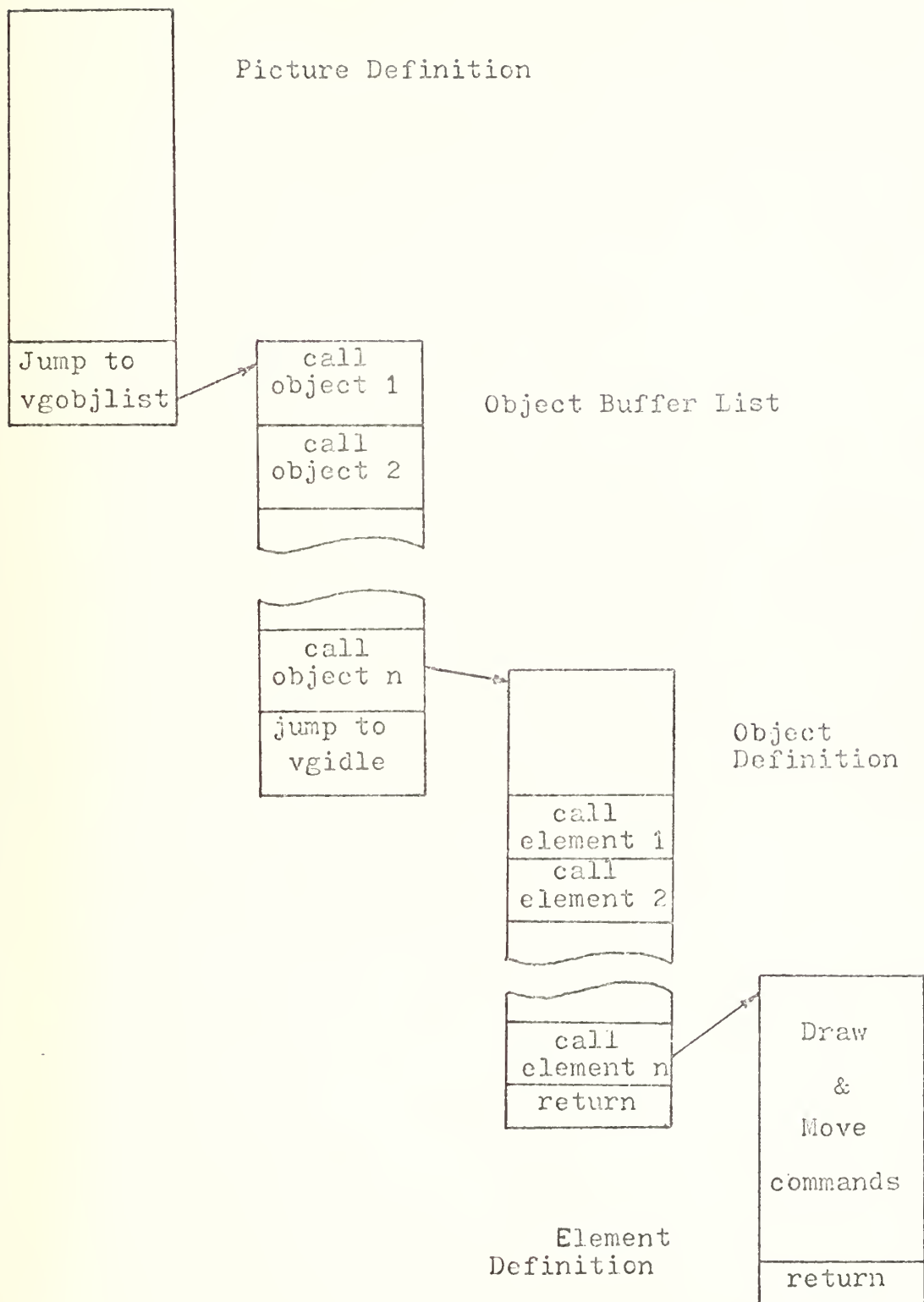


Figure 5-1. Data Structure of the Display Interface.

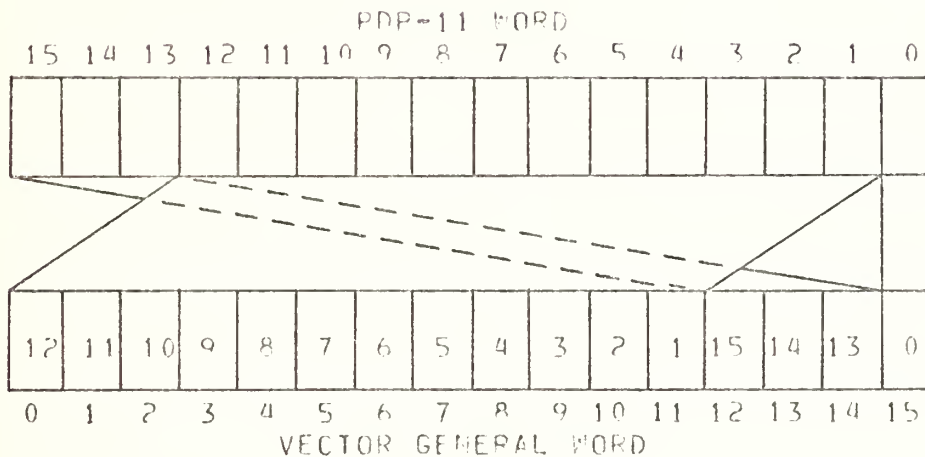
1. Get Real Address Routine (vgcntrl)

Since the vector general uses a DMA channel for display list access, all noncontiguous display lists must be linked by a real PDP-11 address at the point of discontinuity. This routine takes the contents of the input parameter, `addr`, and converts it to a real PDP-11 address in a format acceptable to the vector general. The address is passed to the system routines by the routine `vgpio()`. The same routine is called to return the real address in the variable `raddr`. The returned address is not acceptable to the vector general. The bit manipulation necessary to convert the real address into the vector general memory address register (MAR) format is shown in Figure 5-2.

2. Get User Space Address Routine (vaconvt)

The interface routines maintain no record of the user's element addresses. Therefore, when a display construct is modified, the user space address of the elements involved must be obtained. The MAR format address found in the active display list is converted back to a user space address by this routine. The contents of the parameter `abp` (a MAR format address), is first converted back to a real PDP-11 address (see Figure 5-2). Since the display process is real-time and locked in memory, the

base address of the process remains constant. A call to `vqpio()` returns the process block number in the variable `base`. The block number is then converted to the process base address by multiplying by sixty-four (sixty-four bytes per block). The difference between the process base address and the real PDP-11 address is the user space address offset by the size of the user vector. The user vector is a structure containing all the per process data that does not need to be referenced while the process is swapped. Subtraction of the user vector offset yields the user space address.



The numbers within the vector general word are the bit numbers of the PDP-11 word.

Figure 5-2. PDP-11 to Vector General MAR Format.

3. Modify Element Routine (vgelemod)

The only dynamic system modifications that can be performed on an element is to set or clear the blink mode and light pen hookability.

The element defined by the contents of the parameter, num, is located by a sequential search of elements. The name byte field is compared with the input parameter, num. If a match is found, the value of the field bits are OR'ed or AND'ed into the element depending upon the value of the parameter, action. If action is a zero, the field bits are OR'ed into the element. If action is a one, the complement of the field bits are AND'ed into the element.

The routines possible return codes are:

- 0 - Normal return
- 2 - The element described in the input parameter does not exist
- 4 - The value of the element number is non-positive or greater than two hundred fifty-six, the maximum number of elements permitted by the name byte field of the vector general.

The error codes are chosen to be consistent throughout all the interface routines.

4. Modify Object Routine (vobjmod)

Object modification is more complex than the element modification, because of the number of parameters that may be varied. The structure member, `vgnum`, of each object is compared with the input parameter, `num`, until a match is found. There is no requirement the object exist in the active display list. If, however, the object is part of the active display, a copy of the object is made into `vgworkbuf[]`. `vgworkbuf[]` is then linked to the active display list while the original object is modified.

The bit values of the input parameter, `fields`, determine which parameters are to be modified. The octal number representing the bit position of field and the resulting operation is as follows:

- 0 - Use the contents of `vgffrot[]` as the new values of the rotation matrix.
- 01 - The value of `vgfcsr` is taken as the new value of the coordinate scale register.
- 02 - The values of `vgfcdxr`, `vgfdyvr`, and `vgfdzr` are assumed to be the current values of the X, Y, and Z coordinates respectively.
- 010 - The new intensity offset value is obtained from `vgfior`.
- 020 - `vgfeisr` is the new value of the intensity scale.
- 0400 - The light pen halt interrupt is set or cleared

depending upon the value of the input parameter, action.

01000 - Display blink for the object is set or cleared as determined by the value of action.

020000 - The light pen interrupt is enabled or disabled depending upon the value of action.

After all modifications have been completed, the modified display list is again linked to the active display list.

The possible return codes are:

- 0 - Normal return
- 1 - The value of the object number parameter is non-positive or greater than NOBJ, the maximum number of objects.
- 2 - The object described in the input parameter does not exist.

5. Object Initialization Routine (vqoinit)

This routine is called as part of the program initialization routine, vqinit(), to initialize the object structures and link the components of the display list. Since no objects are included at program initialization, only vqidle is linked to the display list. vqidle is a vector general HALT instruction used to keep the vector general from accessing data outside of the defined display lists. Each object is initialized with vector general instructions

permitting the following dynamic modifications:

Change the nine register rotation matrix

Vary the twelve bit X, Y, and Z coordinate displacements

Modify the five bit intensity offset register

Change the twelve bit intensity scale register

Each object is treated as a subroutine of the object buffer list, `vgobjlist[]`. Therefore, the last executable instruction of each object is a return subroutine jump. Since the initialized object has no elements, the first element of each object is initialized to a load MAR from stack instruction (044016). This instruction causes the vector general to get the next display instruction from `vgobjlist[]`.

6. Open Device Routine (vgopen)

This routine opens all six minor devices and saves the file descriptors for later use by `vgpio()` and `vgterm()`. The file descriptor variables for the various minor devices are:

`vgcmd` - minor device zero

`vgdisp` - minor device one

`vgctrl` - minor device two

`vgfnsw` - minor device three

`vgdial` - minor device four

`vgcnvt` - minor device five

If a device cannot be opened an error message is printed.

7. Picture Modification Routine (vpicmod)

When the user desires to modify the blink or light pen modes of the picture, this routine performs the modification. If bit nine of the input parameter, field, is set, the blink mode of each element is modified according to the value of the input parameter, action. Bit eight and thirteen of field affect the light pen hookability of the picture.

8. P10 Execution Routine (vpio)

vpio() is called by all routines needing to communicate with the vector general. The input parameter, bp, is the address of the buffer used for the read or write operation. The second parameter, mode, is a coded description of the desired operation. The value and purpose of each mode is as follows:

- 1 - Read operation using minor device zero (CMD+READ).

Used in conjunction with mode 2 to convert a user space address to a real address. The buffer, bp, is a pointer to a receptor for the real address.

- 2 - Write operation using minor device zero (CMD+WRITE).

The address of bp is sent to the system routines for conversion from a user space address to a real address.

- 3 - Read operation using minor device one (DISP+READ).

This read operation will return the eighty-three vector general register values as stored by the system routines to the eighty-three words beginning at address bp. Normally this mode is used to return the interrupt register value.

5 - Read operation using minor device two (CTRL<READ).

Similar to mode three except the current values of the vector general registers (not the dial values) are extracted from the vector general prior to sending them to the caller.

6 - Write operation using minor device two (CTRL<WRITE).

The contents of bp, refresh rate, is sent to the system routines to define the refresh reference count.

7 - Read operation using minor device three (FNSW<READ).

Similar to mode three except the current values of the function switches are extracted from the vector general prior to the read operation.

8 - Unused

9 - Read operation using minor device four (DIAL<READ).

Similar to mode three except the ten dial position values are extracted from the vector general prior to the read operation.

NOTE: The dial positions are analog devices. The conversion from analog to digital requires sixteen microseconds per dial.

10 - Unused

11 - Read operation using minor device five (CNVT+READ).

This operation is used with the real to user space address conversion. The buffer pointer, bp, is the receptor for the block number representing the beginning of the real-time process.

12 - Unused

Prior to any read or write operation the value of bp is checked for zero. The caller is prevented from reading or writing using address zero. The read or write operation using address zero can cause the operating system to fail.

B. USER ROUTINES

1. Add Element Routine (voaddele)

A user defined element is linked to a previously defined object by this routine. The address of the user element buffer is the parameter, abp. The input parameter, size, is the number of bytes in the user's element buffer.

NOTE: The user is required to provide six unused bytes with each element. The six bytes (three words) must succeed the draw-move commands.

The value of size is a byte count so as to follow the convention established for PDP-11 system calls. The byte count must also be even to satisfy the word addressing requirement of the vector general.

If the byte count is even and greater than six, a sequential search of all object structures is initiated. The structure member, vnum, is compared with the input parameter, num. When a match is found, a search of that object's elements is begun. The element search is conducted in increments of seven because seven words of the object structure are required to link each element to the object. The search key is the word having the name byte of the user element. The search is completed when the key word is zero. Before linking the element to the object, the six unused bytes (three words) of the users element buffer are assigned as follows:

Word one - Terminate character mode (024)

Word two - Terminate vector mode (015)

Word three - Load MAR from stack (044016)

The element to be added is always appended to the previously linked elements of the object. Therefore, the word following the new element is set to a load MAR from stack instruction (044016). The seven words linking the element to the object are next assigned as follows:

load NMR (020022)

element number

load MAR (040005)

MCR value (046201)

Store MAR in stack and mark (074216)

Load MAK (040016)

Address of element in MAR format

The value placed in the name byte field (NMR) of the element is returned to the user.

Several conditions could cause an error. The possible error codes and their meanings are as follows:

- 1 - The value of the object number parameter is non-positive or greater than NOBJ, the maximum number of objects.
- 2 - The object described in the input parameter does not exist.
- 3 - The number of previously assigned elements equal NELL, the maximum number of elements per object.
- 4 - The value of the global variable, elenum, is greater than two hundred fifty-six, the maximum number the vector general name byte register can contain.
- 5 - The user element buffer contains less than six bytes or the byte count is odd.
- 6 - The user element buffer address is zero.

2. Add Object Routine (voaddobj)

The object referenced by the parameter, num, is to be added to the active display list buffer, vgobjlist[]. The

object to be added is located by sequentially searching the object structure. When the structure member, `vobjnum`, matches the input parameter, `num`, the desired object has been found. The address of the object is then placed in the variable `ptr`. Next the end of the active display list is found by multiplying `vobjlist[0]` by three. This provides the base for inserting the object. Three words are required to link the object to `vobjlist[]`. The base is the last of the three word group. The three word group is assigned as follows:

Store MAR in stack and mark (074216)

Load MAR (040016)

Address of the object in MAR format

The interface routines are designed to ensure that the objects in `vobjlist[]` are always compact. Therefore, each object addition is at the end of the previously added objects. Since the last link in `vobjlist[]` should always to `voidle`, the `voidle` link must be reassigned immediately following the newly added object. The instruction sequence affecting this link is:

Load MAR (040016)

Address of `voidle` in MAR format

There are four possible return codes for this routine.

0 - Normal return

-1 - The value of the object number parameter is non-

positive or greater than NOBJ, the maximum number of objects.

-2 - The object described in the input parameter does not exist.

-3 - The number of previously defined objects equal NOBJ, the maximum number of objects.

3. Display Blink Routine (voblink)

The display blink bit, MDB, of the MCR register is set or cleared by this routine. The value of the parameter, type, determines whether the picture, an object, or an element is to be affected. The value of the parameter, action, specifies the clear or set operation. The return codes are the same as those of vgobjmod().

4. Set Refresh Rate Routine (vgclock)

The routine vgclock() is the only routine sending a control parameter to the system routines. The contents of the parameter, rate, (the refresh rate in hertz) is converted into an integer number representing the number of 8.33 millisecond interrupts permitted before refreshing the display. This integer must be between zero and nine. The converted value is sent to the system routines via the routine vgpio().

5. Change Coordinate Routine (vccoord)

The values of the X, Y, and Z coordinate displacements are updated from the input parameters by this routine. The x, y, and z input parameters are placed in vcfedx, vcfedy, and vcfedz respectively. The routine vgobjmod() is then called to update the coordinate displacement values. The object affected by the new values is identified by the input parameter, num.

The range of the X, Y, and Z coordinate displacement values is from negative two thousand forty-eight through two thousand forty-seven. The return codes for this routine are those of vgobjmod(). The return codes for this routine are the same as those of vgobjmod().

6. Change Coordinate Scale Routine (vccsr)

The coordinate scale register of an object is updated by this routine. The lower twelve bits of the parameter, val, is assigned to vcfcsr. vgobjmod() is then called to update the coordinate scale of the object given in the parameter, num. The return codes for this routine are the same as those of vgobjmod().

7. Delete Element Routine (vodelele)

Since elements are linked to objects by adding the element address to the element field of an object, the deletion process need only delete the address link. The element to be deleted is located in exactly the same manner as in vgmodele(). In this routine, however, only the object containing the element is modified. To prevent unwanted holes within an object, the address of the last element linked to the object is assigned to the location of the element to be deleted. This deletes the desired element but leaves a duplicate copy of the element in the display list. This duplication is eliminated by changing the last active element field to a load MAR from stack instruction (044016).

The return codes for this routine are:

- 0 - Normal return
- 2 - The element described in the input parameter does not exist
- 4 - The value of the element parameter is non-positive or greater than two hundred fifty-six, the size of the vector general name byte.

8. Delete Object Routine (vodelobj)

Deleting an object requires the address link in the object list buffer, vobjlist[], to be cleared and the

remaining objects links to be compacted.

The object to be deleted is located by sequentially searching the object structures for the object with the structure member, `vgnum`, matching the input parameter, `num`. The object list buffer is then searched to determine if the object is currently in the active display list. If the object is currently in the active display list, the address of the last object in `vgobjlist[]` is copied to the address of the object to be deleted. This last object in `vgobjlist[]` is then deleted by a load `MAK` from stack instruction (044016). The structure member, `vgnum`, is reset to zero making the object available for further use.

The possible return codes for this routine are:

- 0 - Normal return
- 1 - The value of the object number parameter is non-positive or greater than `NOBJ`, the maximum number of objects.
- 2 - The object described in the input parameter does not exist.

9. Get Dial Values Routine (vgdial)

This routine obtains the vector general dial values and returns them to the caller. The twelve bit dial values are returned to the caller in a ten word buffer provided by the caller. The contents of the parameter, `abp`, is the beginning address of the buffer.

10. Get Character Routine (vggetcar)

The keyboard input flag, `vgkflag`, set by the keyboard interrupt handler, `vgkbiv()`, is checked. If it is zero, a minus one is returned to the caller. If it is non-zero, `vgkflag` is decremented and the value of `vgkquefl` is used as a pointer into the circular keyboard character queue, `vgkque`, to fetch the ASCII character for the caller.

11. Get Function Switch Routine (vggetfsw)

Two vector general register words, `vgefs1` and `vgefs2`, are returned to the user beginning at the buffer, `abp`. Each bit position of the returned words is the value of one function switch. If a bit is set, the function switch has been depressed. The first two rows of the function device are contained in `vgefs1`. The last sixteen function switches are retained in `vgefs2`.

12. Get Light Pen Interrupt Values Routine (vggetlpp)

The values of the following vector general registers are read sequentially into the buffer `abp`.

`vgepir` - priority interrupt register

`vgfir` - instruction register

`vgfwr` - word count from start of display

`vgfxr` - twelve bit X-coordinate displacement

vgfyr = twelve bit Y-coordinate displacement
vgfzr = twelve bit Z-coordinate displacement
vgfpenr = one bit pen hit resolution count

13. Display List Initialization (voinit)

The voinit() routine performs all display list initialization and default parameter assignment. The user process is made real-time as part of the call to vgoopen(). If vgoopen() can not make the process real-time or access all the minor devices, the user process is terminated without further initialization.

After successfully accessing the vector general minor devices, all of the data structure buffers are assigned default values and linked to form a bare bones display system. At this point the display could be run and all interrupts would be processed.

The following default picture parameters are set at display initialization:

- All function switches are cleared.

- The refresh rate is set to forty hertz.

- The frame clock, keyboard, and manual interrupts are enabled.

- The display is enabled.

- Maximum picture scale is set.

- Post X and post Y displacement values are set to zero.

14. Set Intensity Offset Routine (vaoifset)

The input parameter, *val*, is placed in *vgfior* and the object modification routine, *vgobjmod()*, is called to update the intensity offset register of the object referenced by the input parameter, *num*. The return codes for this routine are those of *vgobjmod()*.

15. Set Intensity Scale Routine (voiscal)

The input parameter, *val*, is placed in *vgfiscr* and the object modification routine, *vgobjmod()*, is called to update the intensity scale register of the object referenced by the input parameter, *num*. The return codes for this routine are those of *vgobjmod()*.

16. Set Function Switch Lamps Routine (volamps)

The four successive words beginning at the buffer address *abp* are assigned the four vector general function switch registers *vgsefs1*, *vgsefs2*, *vgsefs3*, and *vgsefs4*.

17. Set Light Pen Enable (volpen)

The light pen hookability of an element or object is set or cleared by this routine. If the input parameter, *type*, is a zero, the values of the input parameters, *num*

and action, are passed to the picture modification routine, `vpicmod()`. If type is a one, the parameters are passed to the object modification routine, `voobjmod()`. A type of two will modify the element, num, by calling `vgelemod()`. The return codes are those of the modification routine called.

18. Make Object Routine (vomkobj)

This routine initializes an object structure for display use. Before the object can be used, it must be initialized to the system default parameters. The default parameters are:

Maximum intensity offset

Constant intensity scale

One-half coordinate scale

Zero for the X, Y, and Z coordinate displacement

Zero rotation

Same interrupts as set by the `vginit` routine

An unused object is found by searching the object structure until an object is found with a zero assigned as the structure member, `vqnum`. The instructions and default parameters are assigned to the structure and an object number is assigned from the global variable `vgcurobj`. The caller is given the new object number as a return value.

A possible error return code is:

-5 - The number of previously defined objects equal NOBJ, the maximum number of objects.

19. Start Display Routine (vopicture)

The beginning address of the display list, vopldfsl, is passed to the vector general.

20. Change Post X and Post Y Displacement Routine (vopost)

The lower twelve bits of the input parameters, px and py, are assigned to the vector general register voppxr and vopyr respectively.

21. Change Picture Scale Routine (vopscal)

The picture scale is changed to the twelve bit value of the input parameter, val.

22. Rotate Routine (voprotate)

The input parameters x, y, and z are the radian measure of the rotation about the X, Y, and Z axis respectively. The necessary calculations to change the nine register rotation matrix are performed here. The final values entered into the rotation matrix represent the trigonometric

values corresponding to the requested rotation about each axis. The rotation matrix of the object referenced by the input parameter, num, is updated to reflect the new rotation.

23. Terminate The Display (voterm)

The vector general is cleared, the minor devices are closed, and the process is made non real-time. This is the final interface call by the user.

APPENDIX A DATA STRUCTURE FORMATS

Picture Parameter Format

<u>Instruction</u>	<u>Function</u>
0 4 0 0 0 0	Load Lamps
0 0 0 0 0 0	Lamps 0-15
0 0 0 0 0 1	Lamps 16-32, term.
0 4 0 0 2 1	Load Pic Scale
0 7 7 7 6 1	Pic Scale, term.
0 4 0 0 4 7	Load Post Disp.
0 0 0 0 0 0	X Displacement
0 0 0 0 0 1	Y Displacement, term.
0 4 0 0 5 7	Load Lit pen enable
0 0 0 0 0 3	Enable lit pen, term.
0 4 0 0 6 4	Load Lamps
0 0 0 0 0 0	Lamps 16-23
0 0 0 0 0 1	Lamps 24-31, term.
0 4 0 0 1 7	Load Stack Pointer
0 0 0 0 0 1	Stack Address, term.
0 4 0 0 1 6	Load Mem. Addr
0 0 0 0 0 1	Object Buffer Addr, term.

Object Buffer Format

Instruction

0	0	0	0	0	0
0	7	4	2	1	0
0	4	0	0	1	0
0	0	0	0	0	1
0	7	4	2	1	0
0	4	0	0	1	0
0	0	0	0	0	1

Function

Num of objects active
Store MAR in Stack & Mark
Load MAR
Object 1 address, term.
Store MAR in Stack & Mark
Load MAR
Object 2 Address, term.

0	7	4	2	1	0
0	4	0	0	1	0
0	0	0	0	0	1
0	4	0	0	1	0
0	0	0	0	0	1

Store MAR in Stack & Mark
Load MAR
Object n Address, term.
Load MAR
vgiole Address, term.

Object Format

Instruction

0	0	0	0	0	0
0	4	0	0	1	4
0	7	7	7	6	0
0	0	0	0	0	1
0	4	0	0	2	3
0	3	7	7	6	0
0	0	0	0	0	0
0	0	0	0	0	0
0	0	0	0	0	0
0	7	7	7	6	0
0	0	0	0	0	0
0	0	0	0	0	0
0	0	0	0	0	0
0	7	7	7	6	0
0	0	0	0	0	0
0	0	0	0	0	0
0	7	7	7	6	1
0	4	0	0	2	2
0	0	0	0	0	1
0	4	0	0	0	5
0	4	6	2	0	1
0	7	4	2	1	6
0	4	0	0	1	6
0	0	0	0	0	1
0	4	0	0	2	2
0	0	0	0	0	1
0	4	0	0	0	5
0	4	6	2	0	1
0	7	4	2	1	6
0	4	0	0	1	6
0	0	0	0	0	1

Function

Object Number
 Load Intensity Offset
 Intensity Offset
 Intensity Scale, term.
 Load Coordinate Scale
 Coordinate Scale
 X-Coordinate
 Y-Coordinate
 Z-Coordinate
 Rotate X/X
 Rotate X/Y
 Rotate X/Z
 Rotate Y/X
 Rotate Y/Y
 Rotate Y/Z
 Rotate Z/X
 Rotate Z/Y
 Rotate Z/Z, term.
 Load Name Byte
 Element Number
 Load MCR
 Enable bits, term.
 Store MAR in Stack & Mark
 Load MAR
 Element 1 Addr, term.
 Load Name Byte
 Element Number, term.
 Load MCR
 Enable bits, term.
 Store MAR in Stack & Mark
 Load MAR
 Element 2 addr, term.

0	4	0	0	1	6
0	0	0	0	0	1
0	4	4	0	1	6

Load MAR
 Element n Addr, term.
 Load MAR from Stack

Element Format

Instruction

0	0	0	0	0	0

Function

User Defined Instruction

0	0	0	0	0	0
0	0	0	0	1	5
0	0	0	0	2	4
0	4	4	0	1	6

User Defined Terminate Inst.

Terminate All Vector Modes

Terminate Character Mode

Load Mar from Stack

APPENDIX B

GLOBAL VARIABLES

All static global variables used through the interface routines are contained in the four files listed here.

vgglob.h

```

1  int vgkque[NKQUE];           // queue holding the last NKQUE
2                                // ASCII keyboard characters
3
4  int vgstack[NSTACK];         // subroutine stack buffer used
5                                // with VG subroutine jumps
6
7  int vgworkbuf[VGOBJSIZ];     // work buffer for sys mods
8
9  int vglpbuf[7];              // buffer to hold the VG light pen
10                                // interrupt registers
11
12 int vgcurobj;                 // current object number
13
14 int vgidle;
15 char vgkflag;                 // keyboard character flag.
16                                // incremented when ASCII character
17                                // is input
18
19 char vgkptr;                  // pointer to kque location
20                                // receiving the next
21                                // keyboard character
22
23 char vgkquefl;                // kque pointer to the next character
24                                // to be read
25
26 char vgmanint;                // manual interrupt counter
27
28 char vglpflag;                // light pen flag. Set when
29                                // a light pen interrupt occurs.
30                                // Must be cleared by user before
31                                // a second interrupt will be
32                                // processed
33
34 char vglpsflg;                // light pen sense switch flag.
35                                // Set when a light pen interrupt
36                                // occurs and the sense switch is
37                                // depressed.
38
39
40 // system work buffer used to hold the values to be
41 // associated with the vector general register commands
42
43 int vgf_pscal;                // picture scale
44 int vgf_rot[9];               // rotation matrix
45 int vgf_ior;                  // intensity offset
46 int vgf_isr;                  // intensity scale
47 int vgf_csr;                  // coordinate scale
48 int vgf_dxr;                  // X-coordinate
49 int vgf_dyr;                  // Y-coordinate
50 int vgf_dzr;                  // Z-coordinate

```

vgobj.h

```

1 int vgelement;          // current element number
2 int vgobjlist[OLISTSIZ]; // object list buffer
3
4
5 // structure of objects that the user has available for
6 // display
7
8 struct vgobj
9 {
10     int vgnum;           // object number
11     int vglor;           // load intensity offset
12     int vgior;           // intensity offset
13     int vgisr;           // intensity scale, terminate
14     int vglcsr;          // load coordinate scale
15     int vgcscr;          // coordinate scale
16     int vgxr;            // X-coordinate
17     int vgyr;            // Y-coordinate
18     int vgzr;            // Z-coordinate
19     int vgrotr[9];       // rotation matrix
20     int vgele[ELISTSIZ]; // display element buffer
21     int vgnoop;          // no op instruction
22 } vgobj[NOBJ];

```

vgreg.h

```

1 #
2
3 // NOTE: DO NOT ALTER THE ORDER OF THESE VARIABLES
4
5 // The variables in this file correspond to the named
6 // vector general registers. The order is the order in which
7 // the values are assigned by the device driver. The loader
8 // assigns these variables sequentially. Programmatically,
9 // these are treated as a vector.
10
11
12 int vg_fs;           // function switch unit 1
13 int vg_kbr;          // keyboard character
14 int vg_tix;          // tablet x input
15 int vg_tiy;          // tablet y input
16 int vg_pir;          // priority interrupt requests
17 int vg_mcr;          // mode and control (incl int enables)
18 int vg_ir;           // display instruction
19 int vg_wcr;          // word count
20 int vg_xr;           // X-coordinate
21 int vg_yr;           // Y-coordinate
22 int vg_zr;           // Z-coordinate
23 int vg_aicr;         // auto-increment
24 int vg_lor;          // intensity offset (dimming)
25 int vg_isr;          // intensity scale (cueing)
26 int vg_mar;          // memory fetch address
27 int vg_spr;          // stack pointer
28 int vg_tgr;          // temp. general purpose
29 int vg_psr;          // picture scale
30 int vg_nmr;          // name byte
31 int vg_csr;          // coordinate scale
32 int vg_dxr;          // coordinate X displacement
33 int vg_dyr;          // coordinate Y displacement
34 int vg_dzr;          // coordinate Z displacement
35 int vg_r11r;         // rotation matrix X/X scale
36 int vg_r12r;         // rotation matrix X/Y scale
37 int vg_r13r;         // rotation matrix X/Z scale
38 int vg_r21r;         // rotation matrix Y/X scale
39 int vg_r22r;         // rotation matrix Y/Y scale
40 int vg_r23r;         // rotation matrix Y/Z scale

```

```

41     int  vg-r31r;          // rotation matrix Z/X scale
42     int  vg-r32r;          // rotation matrix Z/Y scale
43     int  vg-r33r;          // rotation matrix Z/Z scale
44     int  vg-wmcr;          // window mode control
45     int  vg-xlhr;          // window boundry X high
46     int  vg-xlrl;          // window boundry X low
47     int  vg-ylhr;          // window boundry Y high
48     int  vg-yllr;          // window boundry Y low
49     int  vg-zlhr;          // window boundry Z high
50     int  vg-zllr;          // window boundry Z low
51     int  vg-pdxr;          // post X displacement
52     int  vg-pdyr;          // post Y displacement
53     int  vg-ccr;           // color control
54     int  vg-un1;           // unused
55     int  vg-un2;           // unused
56     int  vg-un3;           // unused
57     int  vg-un4;           // unused
58     int  vg-pirx;          // cx dev priority interr requests
59     int  vg-mcrx;          // ex dev interrupt enables
60     int  vg-penr;          // pen hit resolution count
61     int  vg-un5;           // unused
62     int  vg-un6;           // unused
63     int  vg-un7;           // unused
64     int  vg-fs2;           // function switches unit 2
65     int  vg-kb2;           // keyboard character unit 2
66     int  vg-un8;           // unused
67     int  vg-un9;           // unused
68     int  vg-fs3;           // function switches unit 3
69     int  vg-kb3;           // keyboard character unit 3
70     int  vg-un10;          // unused
71     int  vg-un11;          // unused
72     int  vg-fs4;           // function switches unit 4
73     int  vg-kb4;           // keyboard character unit 4
74     int  vg-un12;          // unused
75     int  vg-un13;          // unused
76     int  vg-pX;            // picture X coordinate
77     int  vg-pY;            // picture Y coordinate
78     int  vg-pZ;            // picture Z coordinate
79     int  vg-Jx;            // joystick X input
80     int  vg-Jy;            // joystick Y input
81     int  vg-Jz;            // joystick Z input
82     int  vg-dia1[10];      // dial inputs
83     int  vg-cxr;           // window acquisition X coordinate
84     int  vg-cyr;           // window acquisition Y coordinate
85     int  vg-czr;           // window acquisition Z coordinate

```

vgsys.h

```

1  #
2  // NOTE:   DO NOT ALTER THE CONTENTS OF THIS VECTOR!
3
4  // These variables are the vector general picture initialization
5  // instructions and data words. The loader assigns the variables
6  // sequentially allowing them to be treated as a vector. The
7  // order of the variables cannot be changed without affecting
8  // the operation of the vector general.
9
10
11     int  vgs_ldfs1 {040000}; // load function switch unit 1
12     int  vgs_fs1 {0};        // function switch lamp bits 0-7
13     int  vgs_fs2 {01};       // function switch lamp bits 8-15
14     int  vgs_lpsr {040021};  // load picture scale
15     int  vgs_psr {077761};   // picture scale, terminate
16     int  vgs_ldpd {040047};  // load post diaplacement
17     int  vgs_pdxr {0};       // post X-displacement
18     int  vgs_pdyr {01};      // post Y-displacement, terminate
19     int  vgs_xmcr {040057};
20     int  vgs_xplr {03};
21     int  vgs_lf2 {040064};   // load function switch unit 2

```

```

22     int vgs_fs3 {0};           // function switch lamps 0-7
23     int vgs_fs4 {01};         // function switch lamps 8-15, term.
24     int vgs_lstk {040017};    // load stack pointer
25     int vgs_stk {0};          // stack pointer, terminate
26     int vgs_lmar {040016};    // load memory address register
27     int vgs_mar {0};          // memory fetch address, term.

```

APPENDIX C COMPILE TIME CONSTANTS

The file listed here contains the defined constants used through the interface routines.

vgdef.h

```

1 #
2
3 /*****
4  * NOTE:  beware of the relation that exists between groups      *
5  *        of defines                                              *
6  *****/
7
8 #define NELE      10          // max num of elements per object
9 #define ELISTSIZ  70          // size of element list buffer.
10                                // This is equal to NELE * 7
11 #define VCOBJSIZ  89          // size of work buffer;
12                                // must be 19+ELISTSIZ
13
14 #define NOBJ      10          // max num of objects per picture
15 #define OLISTSIZ  33          // object buffer size. This is
16                                // equal to (NOBJ + 1) * 3
17
18 #define NSTACK    6          // size of subroutine stack
19
20 #define NKQUE     6          // size of keyboard char queue
21
22
23
24 // The following are the read/write defines for I/O
25
26 #define CMD_READ  1          // read vg commands
27 #define CMD_WRITE 2          // write vg commands
28 #define DISP_READ 3          // read display
29 #define DISP_WRITE 4         // write to display
30 #define CTRL_READ 5          // read vg controller
31 #define CTRL_WRITE 6         // write vg controller
32 #define FNSW_READ 7          // read function switches
33 #define FNSW_WRITE 8         // unused
34 #define DIAL_READ 9          // read dial positions
35 #define DIAL_WRITE 10        // unused
36 #define CNVT_READ 11         // get user base address
37 #define KYBD_WRITE 12        // unused
38
39
40
41 #define ROT        0          // rotation matrix
42 #define CSR        1          // coordinate scale
43 #define DXZR       2          // X,Y,Z coordinates
44 #define IOR        3          // intensity offset
45 #define ISR        4          // intensity scale
46 #define PSR        5          // picture scale
47 #define POST       6          // post X,Y coordinates
48 #define MPH        8          // light pen halt
49 #define IEB        9          // display blink
50 #define MEP        13         // enable light pen interrupt
51 #define PIP        5          // light pen interrupt
52 #define SPI        0          // light pen sense switch
53 #define PIK        3          // keyboard interrupt
54 #define PIS        2          // manual interrupt
55
56 #define CLEAR      0          // clear flag
57 #define SET        1          // set flag
58 #define PIC        0          // Picture type
59 #define OBJ        1          // object type
60 #define ELE        2          // element type

```

APPENDIX D DEVICE DRIVER

Described here is the system device driver maintained as part of the operating system. The interrupt service routines for the vector general and the service routines for the open() and close() system calls are contained in this routine.

```

1 #
2 #include "../param.h"
3 #include "../conf.h"
4 #include "../user.h"
5 #include "../buf.h"
6 #include "../proc.h"
7 #include "../scg.h"
8 #include "../system.h"
9
10 #define VG      0           // minor device 0
11 #define VGDISP  1           // minor device 1
12 #define VGCTRL  2           // minor device 2
13 #define VGFSW   3           // minor device 3
14 #define VGDIAL  4           // minor device 4
15 #define VGCONVT 5           // minor device 5
16 #define CLOSE   0           // restrict access flag
17 #define OPEN    1           // permit access flag
18 #define VGADDR  0167770     // PDP-11 address of VG
19 #define SAR0    0           // VG reg command
20 #define SAR1    1           // VG reg command
21 #define SAR52   064         // VG reg command
22 #define SAR70   0106        // VG reg command
23 #define AKC     040000      // ack. frame clock interrupt
24 #define SCL     01000       // stop & clear disp controller
25 #define AKWCSD  0176600     // ack all interpt & reset disp
26 #define BUSY    1
27 #define IDLE    0
28
29 // four I/O channels in the PDP-11
30
31 struct {
32     int ddo;           // direct data output
33     int pio;           // extended prog I/O
34     int ma;            // memory address
35     int pio;           // prog I/O
36 };
37
38 struct buf rvgbuf;
39
40
41 char vglk[0];          // minor device 0 lock
42 char displk[0];        // minor device 1 lock
43 char ctrl1k[0];        // minor device 2 lock
44 char fnswlk[0];        // minor device 3 lock
45 char diallk[0];        // minor device 4 lock
46 char keybdlk[0];       // minor device 5 lock
47 char vglock[0];        // VG system lock
48 char display;          // display active flag
49 char esc[0];           // ASCII escape flag
50 int vgbuf[80];         // VG register buffer
51 int clockcnt;          // frame clock count
52 int clockref[3];       // frame clock ref count
53 int base;              // proc base address
54 int baddr1;            // display base address
55 int baddrx;            // extended memory bits
56 int i;
57 int vgaddr;            // buffer address
58 int vgcore;            // real core address
59 int *vgproc;           // pointer to real time process

```

```

60
61
62 vgopen(dev,flag) {
63     switch (dev.d_minor) {
64         case VG: { // channel for virtual to real
65             if (vglk == OPEN) { // address conversion
66                 u.u_error = EIO;
67                 return;
68             }
69             vglk = OPEN;
70             break;
71         }
72         case VCDISP: { // channel for display lists
73             if (displk == OPEN) {
74                 u.u_error = EIO;
75                 return;
76             }
77             displk = OPEN;
78             break;
79         }
80         case VGCNTRL: { // channel for driver control
81             if (ctrl1k == OPEN) {
82                 u.u_error = EIO;
83                 return;
84             }
85             ctrl1k = OPEN;
86             break;
87         }
88         case VGFNSW: { // channel to obtain function
89             if (fnswlk == OPEN) { // switches
90                 u.u_error = EIO;
91                 return;
92             }
93             fnswlk = OPEN;
94             break;
95         }
96         case VGDIAL: { // channel to obtain dial
97             if (dial1k == OPEN) { // positions
98                 u.u_error = EIO;
99                 return;
100             }
101             dial1k = OPEN;
102             break;
103         }
104         case VGCONVT: { // channel for real to virtual
105             if (keybd1k == OPEN) { // address conversion
106                 u.u_error = EIO;
107                 return;
108             }
109             keybd1k = OPEN;
110             break;
111         }
112         default: {
113             u.u_error = EIO;
114             return;
115         }
116     }
117 if (displk && ctrl1k && fnswlk && dial1k && keybd1k && vglk)
118 {
119     vgproc = u.u_proc;
120 // if(srttime(0) != 0) // make process real time
121 // {
122 //     vgclose();
123 //     u.u_error = EACCES;
124 //     return;
125 // }
126 VGADDR->pio = SCL1AKC; // clear & reset VG
127 vglock = OPEN; // enable VG system
128 display = IDLE;
129 }
130
131
132
133
134 // The Vector General is a dedicated device. Therefore,

```



```

135 //  if one minor device is closed access to all minor devices
136 //  is restricted.
137
138 vgclose(dev) {
139     vglk = CLOSE;
140     vglock = CLOSE;
141     displk = CLOSE;
142     ctrl1k = CLOSE;
143     fnswlk = CLOSE;
144     dial1k = CLOSE;
145     keybd1k = CLOSE;
146     VGADDR->pio = SCL;           // clear & reset VG
147     nonrttime();                // make process non real time
148 }
149
150
151
152
153
154
155 vgstrategy(abp)
156     struct buf *abp; {
157     register struct buf *bp;
158
159     bp = abp;
160     vgcore = bp->b_addr;         // save real address of buf
161     if(display == IDLE)
162     {
163         base = vgproc->p_addr;   // save base address for real
164                                 // to virtual address conversion
165
166         switch(bp->b_xmem)        // set extended memory bits for VG
167         {
168             case 00:             // 0-32k address block
169             {
170                 baddrx = 0;
171                 break;
172             }
173             case 01:             // 32-64k address block
174             {
175                 baddrx = 024;
176                 break;
177             }
178             case 10:             // 64-96k address block
179             {
180                 baddrx = 050;
181                 break;
182             }
183             case 11:             // 96-128k address block
184             {
185                 baddrx = 074;
186                 break;
187             }
188         }
189     }
190     u.u_count = 0;              // make sys believe I/O complete
191     iodone(bp);
192 }
193
194
195
196
197
198
199 vgwrite(dev,flag) {
200     if (vglock == CLOSE) {
201         u.u_error = EBADF;
202         return;
203     }
204     switch (dev.d_minor) {
205         case VGDISP: {           // send display list to VG
206             physio(vgstrategy,&rvgbuf,dev,B_WRITE);
207             baddr1 = vgcore;
208             if(display == IDLE) {
209                 display = BUSY;

```

```

210         vgstart();
211     }
212     return;
213 }
214 case VG: { // save real address
215     physio(vgstrategy, &vgbuf, dev, B_WRITE);
216     vgaddr = vgcore;
217     return;
218 }
219 case VGCNTRL: { // set user refresh rate
220     clockref = cpass();
221     return;
222 }
223 default: {
224     u.u_error = EIO;
225     return;
226 }
227 }
228 }
229
230
231
232
233
234
235
236
237
238
239 vgpascc(abp) // pass data from here to user
240     int abp; // NOTE: user is responsible
241     { // for correct byte count
242     char *bp;
243     bp = abp;
244     while(pascc(*bp) >= 0) bp++;
245     }
246
247
248
249
250
251
252 vgreadd(dev, flag) {
253     if (vglock == CLOSE) {
254         u.u_error = EBADF;
255         return;
256     }
257     switch (dev.d_minor) {
258     case VGCNTRL: { // read VG registers
259         VGADDR->pio = SAR0;
260         for (i=0; i<80; i++) vgbuf[i] = VGADDR->pio;
261         break;
262     }
263     case VGFNSW : { // read VG function switch registers
264         VGADDR->pio = SAR0;
265         vgbuf[0] = VGADDR->pio;
266         VGADDR->pio = SAR52;
267         vgbuf[52] = VGADDR->pio;
268         break;
269     }
270     case VGDIAL: { // read VG dial postions
271         VGADDR->pio = SAR70;
272         for (i=70; i<89; i++)
273             {
274                 if (i<= 100); // waste time
275                 vgbuf[i] = VGADDR->pio;
276             }
277         break;
278     }
279     case VGDISP: { // read last update of VG registers
280         break;
281     }
282     case VGCONVT: { // send real basea address to user
283         vgpascc(&base);
284         return;

```

```

285         )
286     case VG: { // send real address to user
287         vgpasse(&vgaddr);
288         return;
289     }
290     default: {
291         u.u_error = E10;
292         return;
293     }
294 }
295 vgpasse(vgbuff); // send VG registers to user
296 return;
297 }
298
299
300
301
302
303
304 vgststart() {
305     clockent = 0;
306     VGADDR->piox = baddrx; // set VG extended memory bits
307     VGADDR->ma = baddr1; // send VG display address
308     VGADDR->pio = AKWCSD; // start VG operation
309 }
310
311
312
313 // VG frame clock interrupt handler. When enabled frame
314 // clock interrupts occur every 8.33 msec.
315
316 vgclock() {
317     if(vglock == CLOSE) return;
318     VGADDR->pio = AKC; // akc frame clock intrp
319     if(++clockent == clockref) { // refresh the display
320         VGADDR->pio = SCL;
321         vgststart();
322     }
323 }
324
325
326
327
328
329 // The current VG interface software makes no use of the
330 // P-bit. However, the P-bit interrupt handler is required
331 // for system compatibility.
332
333 vgpbit() {
334 }
335
336
337
338
339
340 // VG device interrupt handler. Called whenever
341 // the VG keyboard is depressed, the manual interrupt switch
342 // is depressed, or a light pen interrupt is detected by
343 // the VG.
344
345 vgdev()
346 {
347     if (vglock == CLOSE) return;
348     VGADDR->pio = SAR0; // get VG interrupt state
349     for(i=0;i<11;i++) vgbuff[i] = VGADDR->pio;
350     VGADDR->pio = SAR52;
351     vgbuff[52] = VGADDR->pio;
352     if(!esc)
353     {
354         if(vgbuff[4]&010 88 vgbuff[1] == 012000)
355         {
356             psignal(vgproc,2); // terminate the process
357             goto akc;
358         }
359         if(vgbuff[4]&010 88 vgbuff[1] == 015400)

```

```

360      (
361      esc++;
362      goto akc;
363      )
364      psignal(vgproc,15);          // send the user the interrupt
365      )
366      else esc--;
367 akc:
368      VCADDR->pio = vgbuf[4] << 3;    // acknowledge interrupt
369      )

```

APPENDIX E INTERFACE ROUTINES

Contained here are the interface routines grouped by files. The files are in alphabetical order.

vgel.c

```

1 #include "vgdef.h"
2 #include "vgglob.h"
3 #include "vgobj.h"
4
5
6
7
8 /*
9  * Add an element to an object. Possible return codes are:
10  *      -1 illegal object number
11  *      -2 nonexistent object
12  *      -3 object cannot access more elements
13  *      -4 element number is out of range
14  *      -5 user display buffer is less than 6 bytes
15  *      -6 user buffer address is zero
16  *      normal return is the element number
17  */
18
19 vga dele(abp,num,size)
20     int abp;           // user element buffer
21     int num;           // object number
22     int size;          // num bytes in user buffer
23 {
24     int i,j;
25     int *bp;           // buffer pointer
26
27     if((bp=abp) == 0) return(-6); // check for buf addr of 0
28     if(size&01 || (size>>1)<=3) return(-5); // check byte count
29     if(num<=0) return(-1); // check object number
30 /*
31  * Search all the object structures for the object.
32  */
33     for(i=0;i<NOBJ;i++) if(vgobj[i].vgnum == num) break;
34     if(i >= NOBJ) return(-2); // object doesn't exist
35 /*
36  * Find the first empty element location in the object
37  * structure.
38  */
39     for (j=1;j<ELISTSIZ;j += 7)
40         if (vgobj[i].vgele[j] == 0) break;
41     if(j==ELISTSIZ) return(-3); // no empty elements
42
43     if((++vgelenum)>256) return(-4); // no empty elements
44 /*
45  * Fill the last 3 words of the element buffer.
46  */
47     *(bp + (size-1)) = 044016; // 1d MAR from stack inst
48     *(bp + (size-2)) = 024; // term char mode
49     *(bp + (size-3)) = 015; // term all modes except char
50 /*
51  * Fill the element words associated with the object.
52  */
53     vgobj[i].vgele[j+6] = 044016;
54     vgobj[i].vgele[j+5] = vgentrl(bp) | 01;
55     vgobj[i].vgele[j+4] = 040016;
56     vgobj[i].vgele[j+3] = 074216;
57     vgobj[i].vgele[j+2] = 046201;
58     vgobj[i].vgele[j+1] = 040005;

```

```

59     vgobj[il].vgele[j]    = (vgelenum<<8)|01;
60     vgobj[il].vgele[j-1] = 040022;
61     return(vgelenum);
62 }
63
64
65
66
67
68
69
70
71
72
73 /*
74 * Delete the element by searching all object structures
75 * for the given element. Possible return codes are:
76 *      0 normal return
77 *     -2 element does not exist
78 *     -4 element number is out of range
79 *
80 */
81 vgelele(num)
82     int num;                // element number
83 {
84     int i,j;
85
86     if(num<=0 || num>256) return(-4); // check element num
87 /*
88 * Sequentially search all object structures and elements for the
89 * object containing the element.
90 *
91 for(i=0;i<NOBJ;i++)
92 {
93     for(j=1;j<ELISTSIZ;j += 7)
94     {
95         if(vgobj[il].vgele[j] == 0) break;
96         if (vgobj[il].vgele[j] == ((num<<8)|01)) goto found;
97     }
98 }
99     return(-2);            // element doesn't exist
100 */
101 * Delete the element and compact the remaining elements.
102 *
103 found:
104     while(vgobj[il].vgele[j+7] != 0)
105     {
106         vgobj[il].vgele[j+6] = vgobj[il].vgele[j+13];
107         vgobj[il].vgele[j+5] = vgobj[il].vgele[j+12];
108         vgobj[il].vgele[j+2] = vgobj[il].vgele[j+9];
109         vgobj[il].vgele[j]   = vgobj[il].vgele[j+7];
110         j += 7;
111     }
112     vgobj[il].vgele[j-1] = 044016;
113     vgobj[il].vgele[j] = 0;
114     return(0);
115 }
116
117
118
119
120
121
122
123
124
125
126 /*
127 * Modify the light pen and display blink fields of the MCR
128 * register of element. Possible return codes are:
129 *      0 normal return
130 *     -2 element doesn't exist
131 *     -4 element out of range
132 *
133 */

```

```

134
135 vgelemod(num,field,action)
136     int num;           // element number
137
138     int field;          // 0100    light pen halt
139                        // 01000    display blink
140                        // 020000    light pen hit detect interrupt
141
142     char action;        // 0 - clear
143                        // 1 - set
144
145     {
146         int i,j;
147
148         if(num<=0 || num>NELE) return(-4); // check element number
149 /*
150 * Find the object containing the element.
151 *
152 *
153 */
154     for (i=0;i<ROBJ;i++)
155     {
156         for (j=1;j<ELISTSIZ;j += 7)
157         {
158             if (vgobj[i].vgele[j] == 0) break;
159             if (vgobj[i].vgele[j] == ((num<<8)|01)) goto found1;
160         }
161     }
162     return(-2);          // element doesn't exist
163
164 /*
165 * Modify the light pen and blink control.
166 *
167 */
168 found1:
169     if(action == SET)
170         vgobj[i].vgele[j+2] =1 field;
171     else if(action == CLEAR)
172         vgobj[i].vgele[j+2] =3 ~(field|0100000);
173     return(0);
174 }

```

vginit.c

```

1 #include "vgdef.h"
2 #include "vgglob.h"
3 #include "vgsys.h"
4 #include "vgobj.h"
5
6
7 extern vgcrash();
8 extern vgd piv();
9
10
11 /*
12 * The vector general initialization routine defines all
13 * system instructions and links all system buffers.
14 *
15 * If the process can't become real-time or if all minor
16 * devices are unable to be opened the process is terminated.
17 *
18 */
19
20 vginit()
21 {
22
23 /*
24 * Open all vector general minor devices.
25 *
26 */
27     if (vgopen() != 0) vgcrash();
28 }

```

```

29 /*
30 * Make the process real-time. This call is placed here
31 * only until the system rtime() call from the driver level
32 * can be debugged. It should be a call at the driver level
33 * when all minor devices are opened.
34 *
35 */
36 if(rtime(0) != 0)
37 {
38     perror("rtime error");
39     vgerash();
40 }
41
42 signal(2,vgerash);
43 signal(15,vgd piv);
44
45 vgclock(40); // set default refresh rate
46
47 vgs_mar = vgoinit()|01; // get address of objlist
48 vgs_stk = vgcnt1(vgstack)|01; // stack addr in MAR format
49 vgstack[9] = vgcnt1(&vgidle)|01; // stack underflow protection
50 vgidle = 030000; // halt instruction
51 vglpflag = 0; // light pen interrupt flag
52 vglpsflg = 0; // light pen sense switch flag
53 vghflag = 0; // keyboard flag
54 vgkptr = 0; // keyboard queue pointer
55 vgekuefl = 0; // keyboard input flag
56 return;
57 )
58
59
60
61
62
63 /*
64 * fill buffer with the post X-coordinate and the post
65 * Y-coordinate values. The values that px and py may assume
66 * are 0177760 (-2048) through 077760 (2047).
67 *
68 */
69 vgpst(px,py)
70     int px; // post X-coordinate
71     int py; // post Y-coordinate
72 {
73     vgs_pdxr = px << 4;
74     vgs_pdyr = py << 4;
75 }
76
77
78
79
80
81 /*
82 * Set/Clear the function switch lamps. Each bit set in the
83 * input buffer will affect one lamp.
84 *
85 */
86 vglamps(abp)
87     int abp; // two word buffer pointer
88 {
89     int *bp;
90     if(abp==0) return(-6);
91     bp = abp;
92     vgs_fs1 = *bp & 0177400;
93     vgs_fs2 = ((*bp & 0377) << 8)|01;
94     vgs_fs3 = *(++bp) & 0177400;
95     vgs_fs4 = ((*bp & 0377) << 8)|01;
96 }
97
98
99
100
101
102 /*
103 * Modify the picture parameters.

```



```

104 * The values field can assume are:
105 *
106 */
107
108 vgpicmod(field,action)
109     int field;          // 0400    light pen halt
110                        // 01000   display blink
111                        // 020000   light pen hit detect interrupt
112
113     int action;          // 0    clear
114                        // 1    set
115
116     {
117     int i;
118
119     i = 0;
120     while(i<NOBJ) vgoobjmod(vgoobj[i++].vgnum,field,action);
121     }
122
123
124
125
126
127 /*
128 * Start the display.
129 *
130 */
131 vgpicture()
132     {
133     vgpio(&vgs_ldfs1,DISP_WRITE);          // start display
134     }
135
136
137
138
139
140 /*
141 * Modify the picture scale. The range of values are 0 - 1.
142 *
143 */
144 vgpscal(val)
145     double val;          // picture scale value
146     {
147     int temp;             // temp integer value
148     temp = val * 2047;
149     vgs_psr = (temp<<4)|01;
150     return(0);
151     }

```

vgintr.c

```

1 #include "vgdef.h"
2 #include "vgglob.h"
3 #include "vgreg.h"
4
5
6 /*
7 * when a light pen interrupt, a sense switch interrupt, a
8 * keyboard interrupt, or a manual interrupt occurs the
9 * VC system interrupt driver passes the interrupt to the
10 * user via this routine.
11 *
12 * NOTE: interrupts are passed via signal 15
13 *
14 */
15 vgdpi()
16     {
17     int i;
18

```

```

19  signal(15,vgdpiv);
20  vgplo(8vg_fs,DISP_READ);          // get interrupt state from VG
21
22  for (i=0;i<7;i++) if((vg_pir>>1)&01) switch(i)
23  {
24
25      case PIP:                      // light pen interrupt
26
27      case SP1:                      // light pen sense switch
28          {                          // interrupt
29              vglpiv();
30              break;
31          }
32
33      case PIK:                      // keyboard interrupt
34          {
35              vgkpiv();
36              break;
37          }
38
39      case PIS:                      // manual interrupt
40          {
41              vgmpiv();
42              break;
43          }
44      }
45  return;
46  }
47
48
49
50
51
52 /*
53 * light pen interrupt handler
54 * store the resulting light pen interrupt values in vglpbuf
55 * only if the previous interrupt has been processed by the
56 * user.
57 *
58 */
59 vglpiv()
60 {
61     if((vglpflag==0) && (vg_pir&01))
62     {
63         vglpbuf[0] = vg_pir>>3;      // mode & control reg
64         vglpbuf[1] = vg_lr;          // instruction word reg
65         vglpbuf[2] = vg_wcr;         // word count reg
66         vglpbuf[3] = vg_xr>>4;       // X-coordinate
67         vglpbuf[4] = vg_yr>>4;       // Y-coordinate
68         vglpbuf[5] = vg_zr>>4;       // Z-coordinate
69         vglpbuf[6] = vg_peur;        // pen resolution byte
70         vglpflag++;
71     }
72     if (vg_pir&01) vglpsflag++;
73 }
74
75
76
77
78
79 /*
80 * Vector General Keyboard Character Pivot
81 * when a keyboard character interrupt has occurred, this routine
82 * gets the keyboard character from the Vector General
83 * places it in vgkque, and increments the character flag,
84 * vgkflag, to indicate a character has been input
85 *
86 * NOTE: The user should empty the queue by calling
87 * vggetcar().
88 *
89 */
90 vgkpiv() {
91     vgkflag++;
92     if (vg_kbr == 010000)
93     {

```

```

94         vgkflag = 0;
95         vgkptr = 0;
96         vgkquefl = 0;
97         return;
98     }
99     if (vgkptr == NKQUE) vgkptr = 0;
100     vgkque[vgkptr++] = vg_kbr;
101 }
102
103
104
105
106 /*
107  * Vector General Manual Interrupt Pivot.
108  * when a manual switch interrupt occurs, this routine increments
109  * the manual interrupt counter
110  */
111
112 vgmpiv() {
113     vgmanint++;
114 }
115
116
117
118
119
120
121
122 /*
123  * kill the process.
124  * called when a condition requires process termination
125  * i.e. "rubout" on the DATAMEDIA terminal or CTRL T
126  * on the vector general keyboard
127  */
128
129 vgcraash() {
130     vgterm();
131     exit();
132 }

```

vgobj.c

```

1 #include "vgdef.h"
2 #include "vgglob.h"
3 #include "vgobj.h"
4
5
6
7
8 /*
9  * Add the object to the active display list.
10  * The possible return values are:
11  *     0    normal termination
12  *    -1    object number is neg., zero, or greater than NOBJ
13  *    -2    object doesn't exist
14  *    -3    object list is full
15  */
16
17 vgaddobj(num)
18     int num;           // object number
19     {
20     int *addr;         // object address
21     int i,j;
22
23     if(num<=0) return(-1); // check object number
24     if(vgobjlist[0]>NOBJ) return(-3); // object list full
25 }
26 * Find the object structure with the desired object number
27 *

```

```

28     for(i=0;i<NOBJ;i++) if(vgobj[i].vgnum == num) break;
29     if(i>=NOBJ) return(-2);          // object doesn't exist
30
31     j = vgobjlist[0] *3;
32     vgobjlist[j+2] = vgentrl(&vgidle)|01;
33     vgobjlist[j+1] = 040016;          // load MAR
34     vgobjlist[j]   = vgentrl(&vgobj[i].vgnum)|01;
35     vgobjlist[j-1] = 040016;          // load MAR
36     vgobjlist[j-2] = 074216;          // store MAR in stack & mark
37     vgobjlist[0]++;
38     return(0);
39 }
40
41
42
43
44
45
46
47
48
49
50 /*
51 * Find the object, delete it, and if in the active display list
52 * compact the resulting active display list. Possible return
53 * values are:
54 *     0    normal return
55 *    -1    object number out of range
56 *    -2    object doesn't exist
57 *
58 */
59 vgdlobj(num)
60     int num;          // object number
61     {
62     int addr;          // address pointer
63     int i,j,k;
64
65     if(num<=0) return(-1); // check object number
66 /*
67 * Sequentially search the object structures until the desired
68 * object can be found.
69 *
70 */
71     for(i=0;i<NOBJ;i++) if(vgobj[i].vgnum==num) break;
72     if(i>=NOBJ) return(-2); // object doesn't exist
73     vgobj[i].vgnum = 0;      // delete the object
74 /*
75 * Check if the object is in the active display list. If yes
76 * the link in vgobjlist must be removed. If no then only the
77 * object number must be zeroed.
78 */
79     addr = vgentrl(&vgobj[i].vgnum)|01;
80     for(j=1;j<vgobjlist[0];j++) if(vgobjlist[j*3]==addr) break;
81 /*
82 * Compact the resulting display list.
83 */
84     if(j<vgobjlist[0])
85     {
86         vgobjlist[0]--;
87         vgobjlist[j*3] = vgobjlist[vgobjlist[0]*3];
88         vgobjlist[vgobjlist[0]*3] = vgentrl(&vgidle)|01;
89     }
90     return(0);
91 }
92
93
94
95
96
97
98
99
100
101 /*
102 * Find an unused object structure and initialize the structure

```

```

103 * to all default parameters. Possible return codes are: *
104 * -3 all objects previously defined *
105 * Normal return is the object number assigned to the new object *
106 * */
107
108 vgmknobj()
109 {
110     int i;
111     /*
112     * Find the first unused object structure.
113     *
114     for(i=0; i<NOBJ; i++) if(vgobj[i].vgnum==0) break;
115     if(i>=NOBJ) return(-3); // all object in use
116     vgobj[i].vgnum = ++vgcurobj;
117     vgobj[i].vgior = 077760; // intensity offset
118     vgobj[i].vgisr = 01; // intensity scale, terminate
119     vgobj[i].vgcsr = 007760; // coordinate scale
120     vgobj[i].vgx = 0000000; // X-coordinate
121     vgobj[i].vgy = 0000000; // Y-coordinate
122     vgobj[i].vgz = 0; // Z-coordinate
123     vgobj[i].vgrot[0] = 077760; // fill rotation matrix
124     vgobj[i].vgrot[4] = 077760;
125     vgobj[i].vgrot[8] = 077761; // terminate
126     return(vgobj[i].vgnum);
127 }
128
129
130
131
132
133
134
135
136
137
138 /*
139 * Modify the object as indicated by the input parameter. *
140 * Possible return codes are: *
141 * 0 normal return *
142 * -1 object number out of range *
143 * -2 object doesn't exist *
144 * */
145
146 vgmobjmod(num, fields, action)
147     int num; // object number
148
149     int fields; // 0 - rotation matrix
150 // 1 - coordinate scale
151 // 2 - X,Y,Z coordinates
152 // 3 - intensity offset
153 // 4 - intensity scale
154 // 8 - light pen halt
155 // 9 - display blink
156 // 13 - light pen interrupt
157
158     char action; // 0 - clear
159 // 1 - set
160
161     {
162     int ptr; // pointer to object to be modified
163     int obj; // ptr. to obj. in obj. hnf. list
164     int i,j;
165     int taddr; // temp MAR addr of object
166     int *addr; // address of an object
167     char active; // object in active display list
168
169     if(num <= 0) return(-1); // check object number
170
171     /*
172     * Sequentially search the object structures for the desired *
173     * object. *
174     *
175     for(ptr=0; ptr<NOBJ; ptr++) if(vgobj[ptr].vgnum == num) break;
176     if(ptr>=NOBJ) return(-2); // object does not exist
177     /*
178     * Check the active display list for the object to be modified. *
179     *
180     */

```

```

178     addr = 8vgobj[ptr].vgnum;
179     taddr = vgenrl(addr)101;
180     for(obj=1;obj<vgobjlist[0];obj++) if(vgobjlist[obj*3]==taddr)break;
181 /*
182 * Make a copy of the object and link the copy to the active
183 * display list.
184 *
185 active = 0;
186 if (obj < vgobjlist[0])
187 {
188     for(i=0;i<VG0BJSIZ;i++) vgworkbuf[i] = *(addr++);
189     taddr = vgobjlist[obj*3]; // save MAR addr of the org. obj
190     vgobjlist[obj*3] = vgenrl(vgworkbuf)101;
191     active++; // set object active flag
192 }
193 /*
194 * Make the modifications to the original object.
195 *
196 for(i=0;i<16;i++)
197 {
198     if ((fields>>i)801) switch(i)
199     {
200         case ROT: // rotation matrix
201         {
202             for(j=0;j<9;j++) vgobj[ptr].vgrot[j]=vgf_rot[j]<<4;
203             vgobj[ptr].vgrot[8] = 101;
204             break;
205         }
206         case CSR: // coordinate scale
207         {
208             vgobj[ptr].vgcsr = vgf_csr<<4;
209             break;
210         }
211         case DXYR: // X,Y,Z coordinates
212         {
213             vgobj[ptr].vgx = vgf_dxr<<4;
214             vgobj[ptr].vgy = vgf_dyr<<4;
215             vgobj[ptr].vgz = vgf_dzr<<4;
216             break;
217         }
218         case IOR: // intensity offset
219         {
220             vgobj[ptr].vgior = vgf_ior<<4;
221             break;
222         }
223         case ISR: // intensity scale
224         {
225             vgobj[ptr].vgisr = (vgf_isr<<4)101;
226             break;
227         }
228         case MPH: // light pen halt
229         case MDB: // display blink
230         case MEP: // enable light pen
231         {
232             if(action==SET)
233                 for (j=1;j<ELISTSIZ;j+= 7)
234                 {
235                     if(vgobj[ptr].vgele[j]==0) break;
236                     vgobj[ptr].vgele[j+2] = 11<<i;
237                 }
238             if(action == CLEAR)
239                 for(j=1;j<ELISTSIZ;j+= 7)
240                 {
241                     if(vgobj[ptr].vgele[j]==0) break;
242                     vgobj[ptr].vgele[j+2]=8 ~((1<<i)10100000);
243                 }
244             break;
245         }
246         default:
247         {
248             break;
249         }
250     }
251 }
252 if (active) vgobjlist[obj*3] = taddr;

```

```

253     return(0);
254 }
255
256
257
258
259
260
261
262
263
264
265 /*
266  *   initiate the object buffer list and fill all constant
267  *   fields.
268  *
269  */
270 vgoinit()
271 {
272     int i;
273     int j;
274
275     j = 1;
276     vgcurobj = 0;
277     vgelcnum = 0;
278
279 /*
280  *   Initialize the object list buffer
281  *
282  */
283     vgobjlist[0] = 1;           // set first object number
284     vgobjlist[1] = 030000;      // halt
285
286 /*
287  *   Initialize each object structure
288  *
289  */
290     for(i=0; i<NOBJ; i++)
291     {
292         vgobj[i].vglior = 040014; // load intensity offset reg
293         vgobj[i].vglesr = 040023; // load coordinate scale reg
294         vgobj[i].vgelel[0] = 044016; // load MAR from stack
295     }
296     return(vgctrl(vgobjlist));
297 }

```

vgpio.c

```

1 #include "vgdef.h"
2
3     int vgctrl;           // controller file descriptor
4     int vgdials;          // dials file descriptor
5     int vgdisp;           // display file descriptor
6     int vgfns;            // function switch file descriptor
7     int vgcvt;            // keyboard file descriptor
8     int vgcmd;            // command file descriptor
9
10 /*
11  *   Convert the display list address into a user space address
12  *
13  */
14 vgcvt(abp)
15     int abp;              // display list address pointer
16     {
17         int bp;
18         int base;          // base block number of process
19         int page;          // most sig 3 bits of address
20         int virtual;       // user space address
21

```

```

22 /*
23 * Convert the display list address into a real address
24 *
25 */
26     page = (abp & 016) << 12;
27     abp = (abp >> 3) & 017776;
28     bp = abp | page;
29
30 /*
31 * Get the base block number of the process
32 *
33 */
34     vgpio(8base, CNVT_READ);
35
36 /*
37 * Convert the block number into an address and convert the real
38 * address into a user space address.
39 *
40 */
41     virtual = (bp - (base << 06)) - 02000;
42     return(virtual);
43 }
44
45
46
47
48
49 /*
50 * Convert the user space address into a real address in MAR
51 * format.
52 *
53 */
54 vgentrl(addr)
55     int addr;                // user space address pointer
56     {
57         int *laddr;          // logical address
58         int raddr;           // real address
59         int mar;             // VG memory address register
60         laddr = addr;
61
62 /*
63 * Get the real address of the user space address
64 *
65 */
66         vgpio(laddr, CMD_WRITE);
67         vgpio(&raddr, CMD_READ);
68
69 /*
70 * Convert the real address into MAR format.
71 *
72 */
73         mar = (raddr) >> 12;
74         mar = 8 016;
75         mar = 1 (raddr << 3);
76         return(mar);
77     }
78
79
80
81
82
83 /*
84 * Open each of the minor devices and retain the file
85 * descriptors. The minor device number and the file descriptor
86 * associated with it is:
87 *
88 *      0    vgcmd    /dev/vg
89 *      1    vgdisp   /dev/vgdp
90 *      2    vgentrl  /dev/vgct
91 *      3    vgfnsw   /dev/vgfs
92 *      4    vgdials  /dev/vgdl
93 *      5    vgenvt   /dev/vgkb
94 *
95 */
96 vgopen()
97     {

```



```

97     if ((vgcmd = open("/dev/vg",2)) < 0)           // minor device 0
98     {
99         perror("open vgcmd error");
100        return(-7);
101    }
102    if ((vgdisp = open("/dev/vgdp",2)) < 0)         // minor device 1
103    {
104        perror("open vgdisp error");
105        return(-2);
106    }
107    if ((vgctrl = open("/dev/vgct",2)) < 0)         // minor device 2
108    {
109        perror("open vgctrl error");
110        return(-3);
111    }
112    if ((vgfnsw = open("/dev/vgfs",0)) < 0)         // minor device 3
113    {
114        perror("open vgfnsw error");
115        return(-4);
116    }
117    if ((vgdials = open("/dev/vgdl",0)) < 0)        // minor device 4
118    {
119        perror("open vgdials error");
120        return(-5);
121    }
122    if ((vgcnvt = open("/dev/vgkb",0)) < 0)         // minor device 5
123    {
124        perror("open vgcnvt error");
125        return(-6);
126    }
127    return(0);
128 }

```

```

129
130
131
132
133
134/*
135 * Vector General Read/Write Routine
136 * all communication with the vector general is handled via this
137 * routine. The mode determines the action to be taken.
138 * The acceptable values for the mode are:
139 *     1 - read using minor device 0
140 *     2 - write using minor device 0
141 *     3 - read using minor device 1
142 *     4 - write using minor device 1
143 *     5 - read using minor device 2
144 *     6 - write using minor device 2
145 *     7 - read using minor device 3
146 *     8 - write using minor device 3
147 *     9 - read using minor device 4
148 *    10 - write using minor device 4
149 *    11 - read using minor device 5
150 *    12 - write using minor device 5
151 * Return of -1 is the result of an addressing error.
152 *
153
154vgpio(bp,mode)
155     int bp;           // buffer address pointer
156     int mode;         // type I/O operation
157 {
158     int *abp;
159
160/*
161 * Check buffer address. Do not perform the operation is the
162 * address is zero.
163 *
164
165     if(bp == 0) vgcraash();
166
167     abp = bp;
168     switch (mode)
169     {
170         case CMD_READ:           // calc abs address
171             {

```

```

172         if(read(vgcmd,abp,2) < 0)
173             perror("CMD_READ error");
174         break;
175     }
176
177     case CMD_WRITE:                // get abs address
178     {
179         if(write(vgcmd,abp,2) < 0)
180             perror("CMD_WRITE error");
181         break;
182     }
183
184     case DISP_READ:                // get interrupt registers
185     {
186         if(read(vgdisp,abp,166) < 0)
187             perror("DISP_READ error");
188         break;
189     }
190
191     case DISP_WRITE:               // sent display list
192     {
193         if(write(vgdisp,abp,10) < 0)
194             perror("DISP_WRITE error");
195         break;
196     }
197
198     case CTRL_READ:                // get current vg register value
199     {
200         if(read(vgctrl,abp,2) < 0)
201             perror("CTRL_READ error");
202         break;
203     }
204
205     case CTRL_WRITE:               // sent system control words
206     {
207         if(write(vgctrl,abp,2) < 0)
208             perror("CTRL_WRITE error");
209         break;
210     }
211
212     case FNSW_READ:                // get func switch value
213     {
214         if(read(vgfnsw,abp,166) < 0)
215             perror("FNSW_READ error");
216         break;
217     }
218
219     case FNSW_WRITE:               // not used
220     {
221         break;
222     }
223
224     case DIAL_READ:                // get dial positions
225     {
226         if(read(vgdials,abp,166) < 0)
227             perror("DIAL_READ error");
228         break;
229     }
230
231     case DIAL_WRITE:               // unused
232     {
233         break;
234     }
235
236     case CNVT_READ:                // get base address
237     {
238         if(read(vgcnvtf,abp,2) < 0)
239             perror("CNVT_READ error");
240         break;
241     }
242
243     case KYBD_WRITE:               // unused
244     {
245         break;
246     }

```

```

247         default:
248             {
249                 break;
250             }
251     )
252 )
253
254
255
256
257
258 /*
259 *   Terminate vector general operations.   Close all minor devices
260 *   and make the process non real-time.
261 *
262 */
263 vgterm()
264 {
265     if(close(vgdisp) < 0)
266         perror("Close error");
267 }

```

vgrdwri.c

```

1  #include "vgdef.h"
2  #include "vgreg.h"
3  #include "vgglob.h"
4
5
6  /*
7  *   Get the ten vector general dial values.
8  *
9  */
10 vgdial(abp)
11     int abp;                // ten word buffer pointer
12     {
13     int *bp;
14     int i;
15     if(abp==0) return(-6);
16     bp = abp;
17     vgpio(&vg_fs,DIAL_READ);    // get dial values from VG
18     for(i=0;i<10;i++) *(bp++) = vg_dial[i]>>4;
19     }
20
21
22
23
24
25 /*
26 *   get function switch values
27 *   the thirty-two values of the VG function switches
28 *   are returned to the user via the two word buffer.
29 *   A bit that is set corresponds to a VG function switch
30 *   that has been depressed.
31 *
32 */
33 vggetfsw(abp)
34     int abp;                // 2 word buffer
35     {
36     int *bp;
37     if(abp==0) return(-6);
38     bp = abp;
39     vgpio(&vg_fs,FNSW_READ);    // get function switch values
40     *(bp++) = vg_fs;
41     *bp = vg_fs2;
42     }
43
44
45

```

```

46
47
48 /*
49 * Calculate the refresh rate and sent the value to the vector
50 * general. The value sent must be an integer between 0 and 9
51 *
52 */
53 vgelock(rate)
54     int rate;                // refresh rate in hertz
55 {
56     rate = 120/rate;
57     vgpio(3rate,CTRL_WRITE);
58 }

```

vgusr.e

```

1 #include "vgdef.h"
2 #include "vgglob.h"
3 #include "vgreg.h"
4
5 /*
6 * character read routine
7 * Returns the oldest keyboard character in the character queue.
8 * If no character has been input return -1.
9 *
10 * NOTE: The character is filled by a keyboard
11 * character interrupt causing vgkpio() to be called.
12 *
13 */
14 vggetcar()
15 {
16     if(vgkflag == 0) return(-1);
17     vgkflag--;                // removed one character
18     if(vgkquefl == RKQUE) vgkquefl = 0;
19     return(vgkque[vgkquefl++]>>8);
20 }
21
22
23
24
25
26 /*
27 * Set/clear the blink mode on the picture, object, or element.
28 *
29 */
30 vgblink(type,num,action)
31     char type;                // 0 - picture
32                                // 1 - object
33                                // 2 - element
34
35     int num;                  // 0 - picture
36                                // object or element num
37
38     char action;              // 0 - clear
39                                // 1 - set
40 {
41
42     switch(type)
43     {
44         case PIC:              // SET/CLEAR blink picture
45         {
46             return(vgpicmod(01000,action));
47         }
48         case OBJ:              // SET/CLEAR blink on object 'num'
49         {
50             return(vgobjmod(num,01000,action));
51         }
52         case ELE:              // SET/CLEAR blink on element 'num'
53         {

```

```

54         return(vgelemod(num,01000,action));
55     )
56 )
57 )
58
59
60
61
62
63 /*
64 *   Modify the rotation matrix of the object.  The return values
65 *   are those of the object modification routine.
66 *
67 */
68 vgrodate(num,x,y,z)
69     int num;                // object number
70     double x;               // radian rotation about X-axis
71     double y;               // radian rotation about Y-axis
72     double z;               // radian rotation about Z-axis
73 {
74     double sin();
75     double cos();
76     double sinx,siny,sinz,cosx,cosy,cosz;
77     sinx = sin(x);
78     siny = sin(y);
79     sinz = sin(z);
80     cosx = cos(x);
81     cosy = cos(y);
82     cosz = cos(z);
83     vgf_rot[0] = (cosz*cosy - sinx*siny*sinz)*2047;
84     vgf_rot[1] = (cosy*sinz + sinx*siny*cosz)*2047;
85     vgf_rot[2] = -siny*cosx*2047;
86     vgf_rot[3] = -sinz*cosx*2047;
87     vgf_rot[4] = cosx*cosz*2047;
88     vgf_rot[5] = sinx*2047;
89     vgf_rot[6] = (siny*cosz + sinx*cosy*sinz)*2047;
90     vgf_rot[7] = (siny*sinz - sinx*cosy*cosz)*2047;
91     vgf_rot[8] = cosx*cosy*2047;
92     return(vgobjmod(num,01));
93 }
94
95
96
97
98
99 /*
100 *   Modify the X, Y, and Z coordinates of the object.  The range
101 *   of values are from -2048 (0177777) through 2047 (07777).
102 *   The return codes are those of the object modification routine.
103 *
104 */
105 vgcoord(num,x,y,z)
106     int num;                // object number
107     int x;                  // X coordinate
108     int y;                  // Y coordinate
109     int z;                  // Z coordinate
110 {
111     vgf_dxr = x;
112     vgf_dyr = y;
113     vgf_dzr = z;
114     return(vgobjmod(num,04));
115 }
116
117
118
119
120
121 /*
122 *   Modify the intensity offset of the object.  The range of values
123 *   is from 0 to 1.  The return codes are those of the object
124 *   modification routine.
125 *
126 */
127 vgioffset(num,val)
128     int num;                // object number

```

```

129     double val;                // intensity offset value
130     {
131         vgf_lor = val*2047;
132         return(vgobjmod(num,010));
133     }
134
135
136
137
138
139 /*
140 *   Modify the intensity scale of the object. The range of values
141 *   is from 0 to 1. The return codes are those of the object
142 *   modification routine.
143 *
144 */
145 vgisca1(num,val)
146     int num;                    // object number
147     double val;                // intensity scale
148     {
149         vgf_lsr = val*2047;
150         return(vgobjmod(num,020));
151     }
152
153
154
155
156
157 /*
158 *   Modify the coordinate scale of the object. The range of values
159 *   are 0 to 1. The return codes are those of the object
160 *   modification routine.
161 *
162 */
163 vgcsr(num,val)
164     int num;                    // object number
165     double val;                // coordinate scale value
166     {
167         vgf_csr = val*2047;
168         return(vgobjmod(num,02));
169     }
170
171
172
173
174
175 /*
176 *   Set/clear the light pen hookability of the object or element
177 *   The light pen halt, light pen interrupt, and light pen sense
178 *   switch are all treated as a single unit to be set/cleared.
179 *   Return codes are those of the modification routine concerned.
180 *
181 */
182 vglpen(type,num,action)
183     char type;                 // 1 - object
184                                 // 2 - element
185
186     int num;                   // object or element number
187
188     char action;               // 0 - clear
189                                 // 1 - set
190     {
191         switch(type)
192         {
193             case OBJ:           // set/clear object
194             {
195                 return(vgobjmod(num,020400,action));
196             }
197             case ELE:           // set/clear element
198             {
199                 return(vgelemod(num,020400,action));
200             }
201         }
202         return(0);
203     }

```

```

204
205
206
207
208
209 /*
210 *   Get the light pen interrupt registers.  The light pen
211 *   interrupt flag is cleared so another light pen interrupt may
212 *   be accepted by the light pen interrupt handler.
213 *
214 */
215 vgetlpn(abp)
216     int abp;
217     {
218         int *bp;
219         int i;
220         bp = abp;
221         for(i=0; i<7; i++)
222             *(bp++) = vglpbuf[i];
223         vglpflag = 0;
224     }

```

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